**Version 2.0 - Zephyr**

**Firmware**

Can program =

Online source works =

**Outputs**

PPM out = **OK**

PWM Outputs = **OK**

PPM Signal Timing = **OK**

**Inputs**

PPM in = **OK**

Button Reset = **OK**

Proximity Reset = **OK**

Analog 5 + 6 =

GUI Reset Center = **OK**

**Other**

Reset on Channel # = **OK**

Aux Functions Gyro =

Aux Functions Accel =

Aux Function RSSI =

**Bluetooth Transmitter**

Update Rate PARA =

Update Rate CC2540 =

Update Rate Remote =

Connection Stability PARA =

Connection Stability CC2540 = **OK**

Connection Stability Remote =

**Bluetooth Receiver**

Update Rate PARA =

Update Rate CC2540 =

Update Rate Remote =

Connection Stability PARA =

Connection Stability CC2540 = **Random disconnects - NOT USABLE**

Connection Stability Remote =

Remote Bluetooth Reset =

Remote Bluetooth override channels =

**Others**

Calibration Works =

Output Stability, Holds on Pan = **OK**

Board Rotation = **OK**

**GUI**

GUI Update Rate = **Good ~100ms**

GUI Stability =

Windows 7 =

Windows 8 =

Windows 10 =

Stability over time =

**GUI**